european EUROP robotics technology platform

ECHORD information day Deutsches Museum, Munich – 4th September 2009

www.robotics-platform.eu

ECHORD

Point of view of the European robotics industry

Ulf-Goran Norefors

Vice President, ABB AB Robotics



Agenda

1. Background

- 2. EUROP the European Robotics Technology Platform
- Robotics Visions to 2020 and beyond The Strategic Research Agenda for robotics in Europe
- 4. The way ahead: Challenges & Opportunities

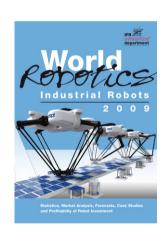


On a Global level

- ISR International Symposium on Robotics
 - annual symposium on industrial and service robotics
 - since 1970



- World Robotics
 - annual statistics of (industrial) robotics
 - since 1985
- IFR International Federation of Robotics
 - established in 1987





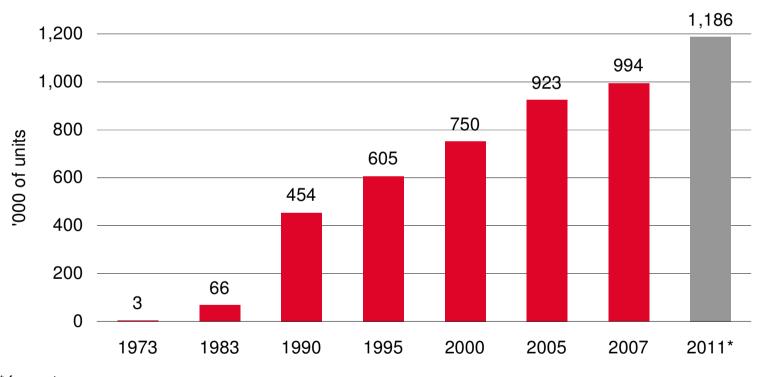
EUnited Robotics the European part of IFR

- EUnited Robotics
 - European Robotics Association
 - Founded in 2004
 - Voice of the European robotics industries
 - Important steps to set up EUROP:
 - Building the ETP European Robotics Platform EUROP
 - Sectorial Report on Industrial Robot Automation
- October 2005: foundation of EUROP



Robotics is a growing Industry 1.2 million industrial robots in 2011

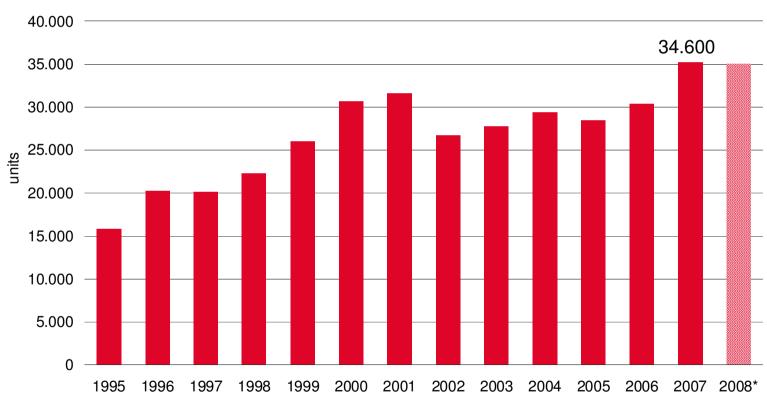
Estimated worldwide operational stock of industrial robots



* forecast Source: World Robotics 2008

Europe has a strong base Every third robot is installed in Europe

Estimated yearly supply of industrial robots in Europe

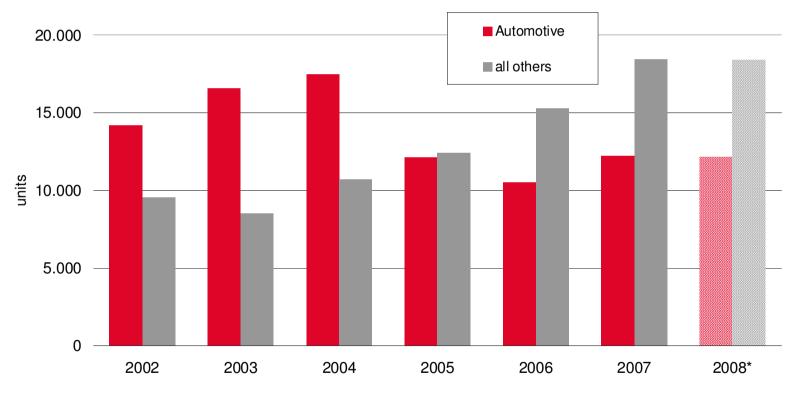


*preliminary results Source: IFR



General Industry applications growing

Estimated yearly supply of industrial robots Automotive and all other industries in Europe



Source: IFR *Preliminary results



Service Robotics

The market is moving.... New products and applications

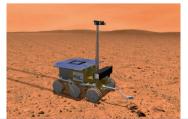
Sales up to 2007

- 49,000 service robots for professional use installed
- about 3.5 million domestic service robots
- 2.0 million entertainment and leisure robots

Forecast 2007 - 2010

- another 35,000 service robots for professional use
- another 3.6 million service robots for private use





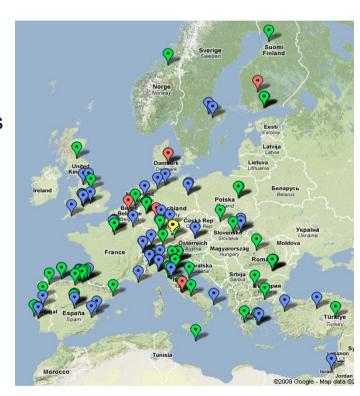


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European Robotics Technology Platform

- An industry driven framework for the European robotics stakeholders
- Founded in October 2005, as one of several European Technology Platforms, supported by the European Commission
- Bringing together the main stakeholders
 - to agree on a common vision for the technology
 - to identify common research and development goals of industrial relevance
- 119 dedicated members & cooperation partners
 - industrial and research organisations active in industrial, professional service, domestic service, security and space robotics
 - From all over Europe



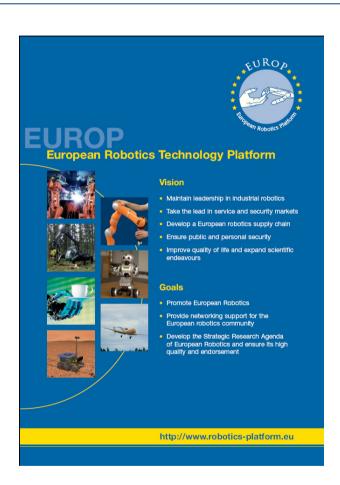
EUROP - Vision & Goals

Vision

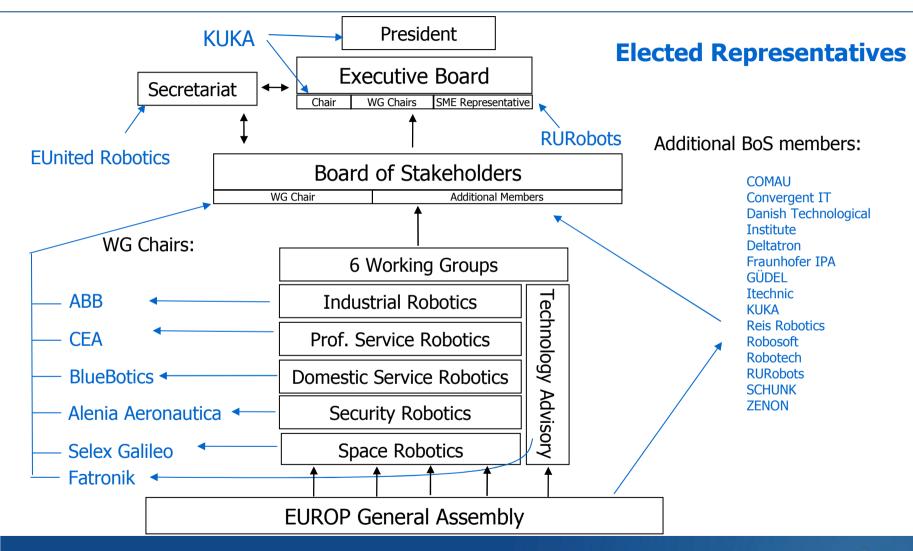
- Maintain leadership in industrial robotics
- Take the lead in service and security markets
- Develop a European robotics supply chain
- Ensure public and personal security
- Improve quality of life and expand scientific endeavours

Goals

- Promote European Robotics
- Provide networking support for the European robotics community
- Develop the Strategic Research Agenda of European Robotics and ensure its high quality and endorsement



EUROP - Governance Structure



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EUROP - Activities

- Networking & Community building: regular meetings, publications, newsletters, etc.
- Enhance the dialogue:
 - Between & across robotics domains
 - Between academia & industry
- Promote European robotics
- Identify & communicate challenges and needs of the European robotics industry

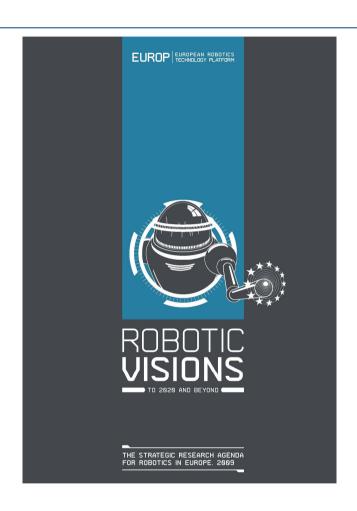
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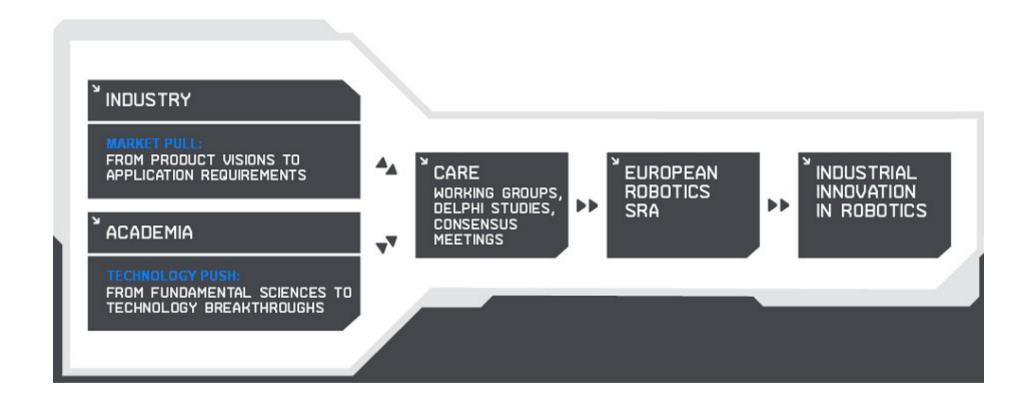
The new EUROP SRA

- Robotic Visions to 2020 and beyond The Strategic Research Agenda for robotics in FUROP
- Presented on July 7th, 2009 in Brussels
- Industry-driven vision, identifying:
 - Future Product Visions of all robotics domains.
 - Opportunities
 - Technology Roadmap
 - Challenges and needs ahead
 - => The implementation of the SRA will lead to industrial innovation in robotics
- http://www.robotics-platform.eu





Setting up a joint Research Agenda for robotics in Europe





Roadmapping methodology

Step 1: Identified 39 Product Visions

Step 2: What level of performance is needed to make

these reality? → Application Requirements

Step 3: Compare Application Requirements of

all Product Visions

→ grouping into Application Scenarios

Step 4: Identify Technologies able to fulfil the

Application Requirements



Step 1: Product visions from all sectors...

Industrial Robotics

RAPIDLY ADAPTABLE MANUFACTURING CELL COORDINATED MOBILE MANIPULATORS

LARGE STRUCTURE MANUFACTURING (INCL. CIVIL ENG.) ROBOT AUTOMATION FOR SMALL SCALE MANUFACTURING

HUMAN-LIKE ASSEMBLY ROBOT MICRO-MANUFACTURING ROBOT

ROBOT ASSISTANT

IN INDUSTRIAL

ENVIRONMENTS

POSTPRODUCTION AUTOMATION (RECYCLING, RE-MANUFACTURING)

ROBOT WITH INTEGRATED PROC-ESS CONTROL Professional Service Robotics

AUTONOMOUS TRANSPORT OF PEOPLE MAINTENANCE ROBOT

MINING ROBOT

FORESTRY AND

AGRICULTURE

UNDERWATER ROBOT

MOTION SIMULATOR

ROBOT TRAINER

TRAINER PROFESSIONAL CLEANING ROBOT

ROBOT GUIDE

ROBOT ASSISTANT FOR PROFESSIONALS

ROBOT TEACHER

SURGICAL ROBOT

AUTONOMOUS REHABILITATION ROBOT OF GOODS

Domestic Service Robotics

PERSONAL ROBOT

ROBOT ASSISTANT FOR PHYSICALLY CHALLENGED

ROBOT COMPANION

ROBOT TOY

Security Robotics

ROBOT ASSISTANT IN SECURITY CONTEXTS

BORDER SURVEILLANCE

SITE PROTECTION (DOMESTIC AND PROFESSIONAL)

SECURITY CHECKS OF GOODS AND PEOPLE

INSPECTION IN ENVIRONMENTS INACCESSIBLE TO HUMANS

DISASTER MANAGEMENT Space Robotics

ORBITAL ROBOT AGENT

PLANETARY ROBOT

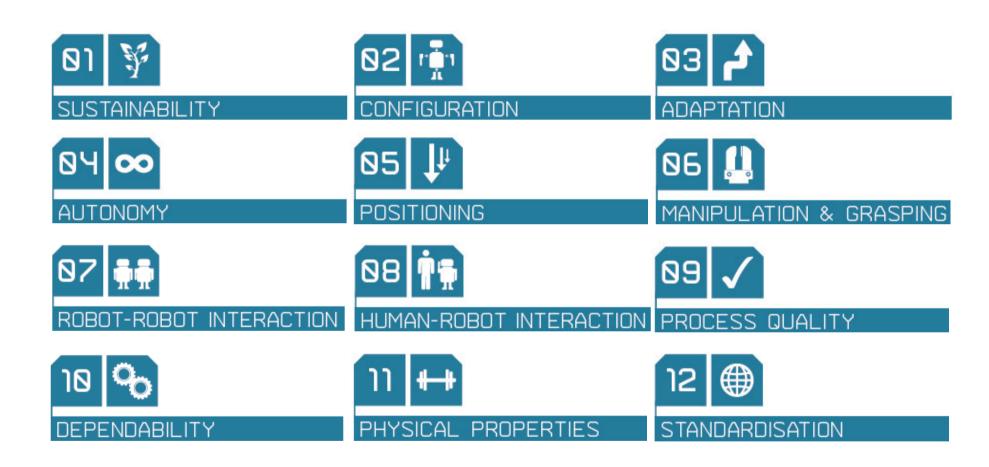
ORBITAL ROBOT ASSISTANT

PLANETARY ROBOT ASSISTANT

ORBITAL ROBOT

PLANETARY ROBOT EXPLORER

Step 2: ...result in 12 Application Requirements...



Step 3: ... leading to Application Scenarios...

Worker

Co-worker

Logistics

Surveillance & intervention & inspection

Exploration

Edutainment



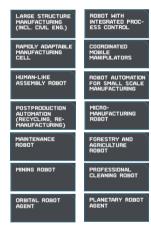










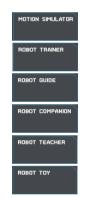






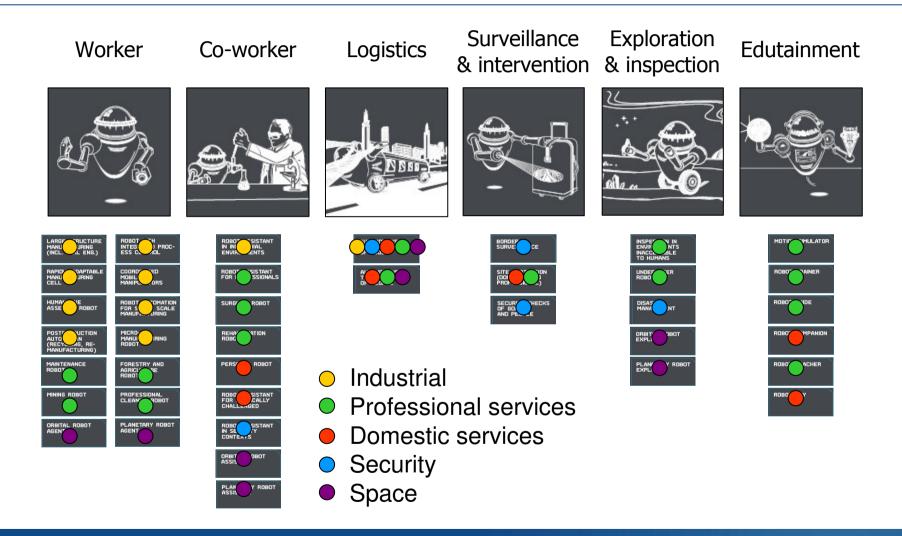






04/09/2009

Step 3: ... covering all market sectors...



04/09/2009

Step 4: 18 Technologies fulfil Application Requirements

Mostly driven by others	Driven by robotics and others		Mostly driven by robotics
SYSTEM ARCHITECTURE	(REAL-TIME) COMMUNICATION	MATERIALS PLANNING	COOPERATING ROBOTS & AMBIENT
POWER MANAGEMENT	HUMAN-MACHINE INTERFACE	CONTROL	INTELLIGENCE
SYSTEM ENGINEERING	SAFETY	LEARNING	END EFFECTORS
MODELLING	LOCOMOTION	SENSORS SENSING 8	NAVIGATION PERCEPTION

Technologies in the SRA

MODELLING

Modelling is the mathematically described approximation of reality.

Most of modelling is driven by other domains, but robotics has a strong need to model and simulate the system (mechanics, actuators, electronics, and sensors) and environment at runtime. Europe is strong in modelling for control (kinematics and dynamics), biomimetics, bionics, and cybernetics.

SHORT TERM (2010)

Lack of standards for model descriptions; simulation not as good as real-world experiments; long computation times

MID TERM (2015)

Standard language for model description; interchangeable models; modelling of flexible and soft bodies; improved cybernetics

LONG TERM (2020+)

Real-time, dynamic modelling and interpretation allow for accurate assessment of the robot's and the world's state

- ← Definition
- Drivers of the technology
- European strengths and weaknesses
- ← 2010: state of the art / short term development
- ← 2015: mid term development
- ← 2020+: long term goals

Ethical, legal, and societal issues

- Ethical issues
 - Robot or robotic device does "wrong"
 - Robot or robotic device is applied inappropriately
- Legal issues
 - Who takes responsibility for the robot's/devices' actions?
- Societal issues
 - Changing labour profiles
 - Social division
- → potential barriers to market



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Bridge gap between industry and academia

- Excellent European research exists in all areas related to robotics, but:
 - Sometimes, there is a big gap between today's industrial needs and academic offerings.
 - Academia has a small scope, component-level focus, working towards just proofs-of-concepts.
 - Research topics are (sometimes) too far directed towards future needs
 - Industry needs system-level applications, with focus on robustness and maintainability.
 - Sometimes industry does not know about useful academic results
 - → Know-how transfer enhance communication:
 - from industry -> academia
 - from academia -> industry



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Opportunities

Inspired by the European Commission join forces in Europe to further grow European Robotics industry

Tools:

The SRA

The refinement of the SRA as lessons are learned

Framework programs

EUROP and **EURON** networks

National Research programs

etc



What industry hopes and expects from ECHORD....

- Bring a lot of latest state-of-the art equipment to robotics labs
- Stimulate academia to solve the research challenges listed in the **EUROP SRA**
- Practical outcomes of the experiments
- Know-how transfer
- Realise new products / solutions
- Build on existing networks: Work with EUROP and EURON towards the implementation of the SRA



The EUROP community
Welcome ECHORD
Look forward to a fruitful cooperation!



european EUROP robotics technology platform

Download the SRA www.robotics-platform.eu/sra